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Key features

At a glance

With free, speed-controlled selection of the gripping positions, flexible access is no longer a problem with the parallel gripper HGPLE. Its long stroke

means it can be used with workpieces of different sizes. The option to adjust the gripping force makes the HGPLE ideal for soft or very delicate workpieces. It also grips large and heavy workpieces reliably.

Economical

- A "pre-holding" position enables the HGPLE to stop its gripper fingers just short of the workpiece, thus reducing access times to an absolute minimum. Even when the size of the workpiece requires the entire
- stroke, the HGPLE still offers impressively short opening and closing times of 0.6 s.
- The installation complexity is minimal as only one cable is required (from the controller to the gripper).

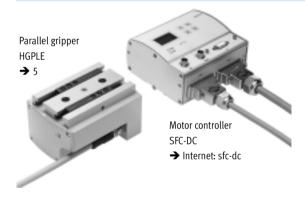
Sturdy

The T-slot gives the HGPLE very high torque resistance as well as very high precision.

Flexible

It is actuated on-site using the tried and tested motor controller SFC-DC.

Everything from a single source



The parallel gripper and motor controller SFC form one unit.

- Thanks to IP54 degree of protection, the SFC can be mounted close to the HGPLE, either:
 - via central supports or
 - via H-rail
- The motor controller SFC is available with or without control panel
- Easy actuation via:
- PROFIBUS
- CANopen
- DeviceNet

Parameterisation possible via:

- Control panel:
 - Suitable for easy positioning sequences
- FCT (Festo Configuration Tool) configuration package:
 - Parameterisation via RS 232 interface
 - Windows-based PC user interface, Festo Configuration Tool
 - Tool is included in scope of delivery



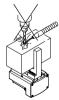


Device**Net**



Note

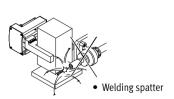
These grippers are not suitable for the following or similar applications:



- Aggressive media
- Machining



• Grinding dust



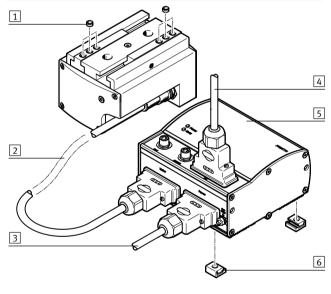
Parallel grippers HGPLE, sturdy with long stroke, electric Key features and peripherals overview

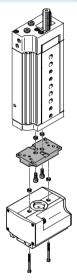
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Mounting options Direct mounting From above From underneath 1 2 2 1 1 Mounting screws 1 Mounting screws 2 Centring sleeves 2 Centring sleeves

Peripherals overview

System product for handling and assembly technology



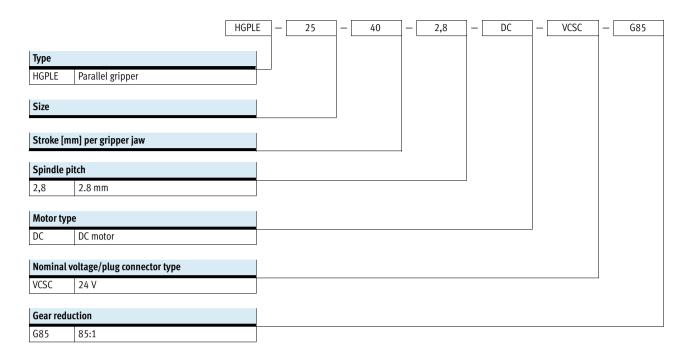


Acces	Accessories								
	Туре	Description	→ Page/Internet						
1	Centring sleeve	For centring attachments	11						
	ZBH								
2	Motor cable	Connecting cable between motor and motor controller	sfc-dc						
	KMTR								
3	Supply cable	Power supply cable; load and logic power supplies are separate	sfc-dc						
	KPWR								
4	Plug connector	For fieldbus interface	sfc-dc						
	FBS, FBA								
5	Motor controller	For parameterising and positioning the parallel gripper	sfc-dc						
	SFC								
6	Central support	- For mounting the motor controller	sfc-dc						
	MUP	- Motor controller can also be mounted on an H-rail							
-	Gripper jaw blank	Unmachined part specially matched to the gripper jaws for custom fabrication of gripper	11						
	BUB-HGPL	fingers							



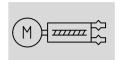
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Type codes



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Function





Size

14 and 25 mm



Stroke 30 ... 80 mm



General technical data								
Size		14		25				
Stroke		30	60	40	80			
Design	Worm gear unit w	vith integrated displacement	encoder					
		Rack and pinion						
Guidance		Plain-bearing gui	ide with T-slot					
Mode of operation		Double-acting						
Gripper function		Parallel						
Number of gripper jaws		2						
Stroke per gripper jaw, adjustable	[mm]	0 30	0 60	0 40	0 80			
Max. load per gripper finger ¹⁾	[g]	150	150	500	500			
Repetition accuracy ²⁾	[mm]	≤ 0.07	≤ 0.07					
Max. interchangeability	[mm]	≤ 0.2						
Reversing backlash ³⁾	[mm]	≤ 0.35						
Rotational symmetry	[mm]	≤ 0.2						
Max. gripper jaw backlash	[mm]	≤ 0.05						
Max. gripper jaw angular backlash	[°]	≤ 0.2						
Homing		Negative fixed stop block						
			Positive fixed stop block					
Position sensing		Via integrated angular displacement encoder						
Type of mounting		Via through-holes and centring sleeves						
		Via female thread and centring sleeves						
Electrical connection		12-pin						
		M12x1						
		Plug connector						
Mounting position		Any						
Product weight	[g]	520	700	1680	2030			

- 1) Applies to unthrottled operation
- 2) End-position drift under constant operating conditions with 100 consecutive strokes in the direction of movement of the gripper jaws
 3) In new condition

Electrical data for motor							
Motor type		DC servo motor					
Nominal operating voltage	[V DC]	24					

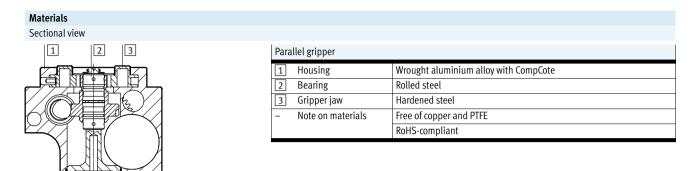
Operating and environmental conditions					
Ambient temperature	[°C]	5 40			
Degree of protection		IP40			
Noise level	[db (A)]	≤60			
CE mark (see declaration of conformity) ¹⁾		To EU EMC Directive			
Corrosion resistance class CRC ²⁾		2			

If the component is subject to restrictions on usage in residential, office or commercial environments or small businesses, further measures to reduce the emitted interference may be necessary. 2) Corrosion resistance class CRC 2 to Festo standard FN 940070

Moderate corrosion stress. Indoor applications in which condensation may occur. External visible parts with primarily decorative requirements for the surface and which are in direct contact with the ambient atmospheric parts with primarily decorative requirements for the surface and which are in direct contact with the ambient atmospheric parts with primarily decorative requirements for the surface and which are in direct contact with the ambient atmospheric parts with primarily decorative requirements for the surface and which are in direct contact with the ambient atmospheric parts with primarily decorative requirements for the surface and which are in direct contact with the ambient atmospheric parts with primarily decorative requirements. sphere typical for industrial applications.

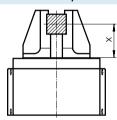
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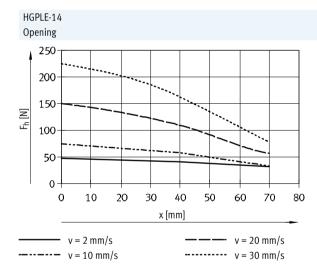
Technical data

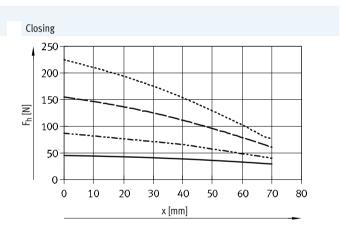


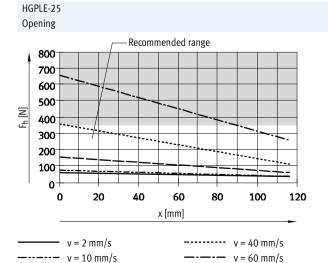
Gripping force F_h per gripper jaw as a function of travel speed v and lever arm x

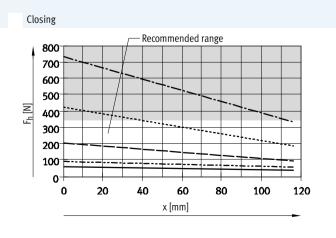
The gripping forces as a function of travel speed and lever arm can be determined using following graphs.









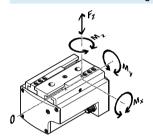


-- v = 20 mm/s

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Total gripping force F with a lever arm X = 20 mm								
Travel speed v	[mm/s]	2	5	10	20	30	40	60
HGPLE-14								
Opening	[N]	92	93	149	300	450	_	-
Closing	[N]	88	104	173	305	445	-	_
HGPLE-25								
Opening	[N]	120	120	148	293	-	652	1150
Closing	[N]	121	120	176	376	-	771	1300

Characteristic load values at the gripper jaws

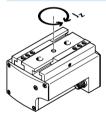


The indicated permissible forces and torques apply to a single gripper jaw. They include the lever arm, additional applied loads due to the workpiece or external gripper fingers and acceleration forces occurring during movement.

The zero co-ordinate line (gripper jaw guide groove) must be taken into consideration for the calculation of

Size	14		25	25	
Stroke		30	60	40	80
Max. permissible force F _z	[N]	500	500	1500	1500
Max. permissible torque M _x	[Nm]	25	35	100	140
Max. permissible torque M _y	[Nm]	25	35	60	90
Max. permissible torque M _z	[Nm]	25	35	70	100

Mass moment of inertia [kgcm²]

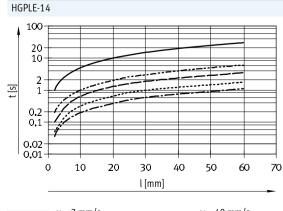


Under the following conditions:

- The reference point is the central
- Without external gripper fingers
- In a load-free state

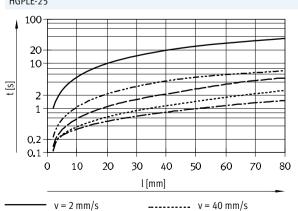
Size		14		25		
Stroke		30	60	40	80	
Mass moment of inertia Jz	[kgcm ²]	4.24	11.64	28.32	72.72	

Positioning time t as a function of stroke per gripper jaw l and travel speed v



---- v = 10 mm/s v = 20 mm/s ----- v = 40 mm/s ---- v = 55 mm/s

HGPLE-25



v = 2 mm/sv = 10 mm/s

----- v = 65 mm/s

v = 20 mm/s

-O- New Size 14/25-80

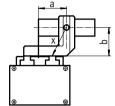
Parallel grippers HGPLE, sturdy with long stroke, electric

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Technical data

Gripping force F_h per gripper jaw as a function of lever arm x and eccentricity a and b

The following formula must be used to calculate the lever arm x with eccentric gripping:



 $x = \sqrt{60^2 + 70^2}$

x = 92 mm

$$x = \sqrt{a^2 + b^2}$$

The gripping force F_h can then be read from the graphs (\Rightarrow 6) using the calculated value x.

Calculation example

Given: Distance a = 60 mm

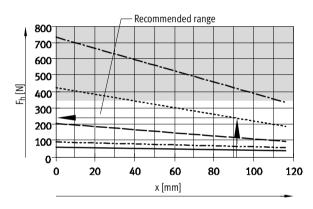
Distance a = 60 mm Distance b = 70 mm

To be found:

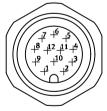
The gripping force at 40 mm/s

with a HGPLE-25-40, used as an external gripper

Approach: The graph $(\Rightarrow 6)$ gives a value for Calculating the lever arm x the gripping force F_h of approx. 245 N.



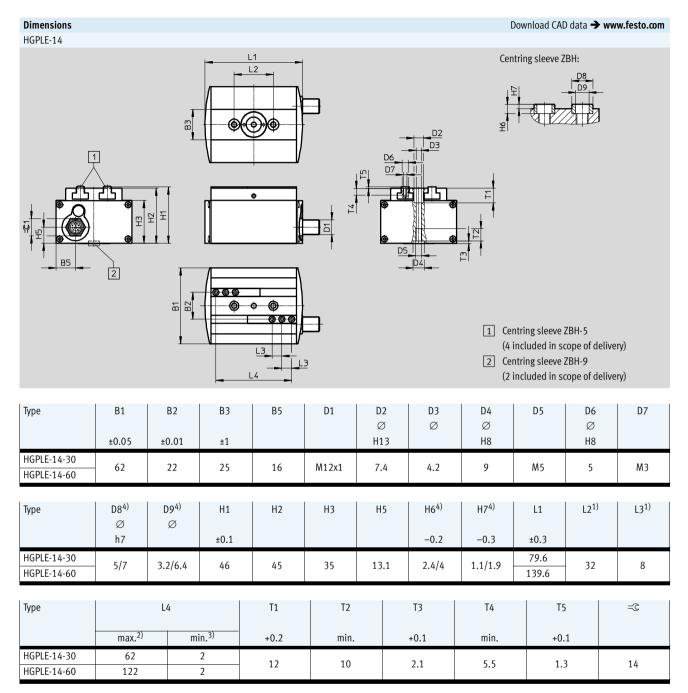
Pin allocation of plug connector



M12	plug connector	
Pin	Port	Function
1	Motor +	Motor conductor
2	Motor –	Motor conductor
3	A	Encoder signal RS 485
4	A/	Encoder signal RS 485
5	В	Encoder signal RS 485
6	B/	Encoder signal RS 485
7	1	Encoder signal RS 485
8	1/	Encoder signal RS 485
9	+5 V DC	Signal supply
10	OV	Signal ground
11	-	Preassigned
12	-	Preassigned



Technical data



¹⁾ Tolerance for centring hole ±0.02 mm Tolerance for thread ±0.1 mm

²⁾ Gripper open

³⁾ Gripper closed

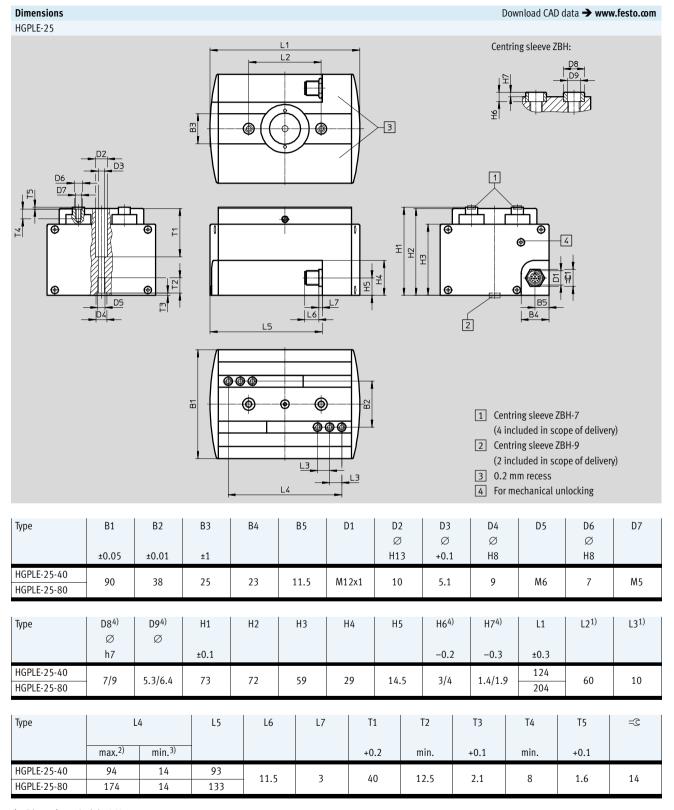
⁴⁾ On the gripper jaw/on the gripper

-⊙- New Size 14/25-80

Parallel grippers HGPLE, sturdy with long stroke, electric



Technical data



Tolerance for centring hole ±0.02 mm Tolerance for thread ±0.1 mm

Gripper open

³⁾ Gripper closed4) On the gripper jaw/on the gripper

Parallel grippers HGPLE, sturdy with long stroke, electric Technical data

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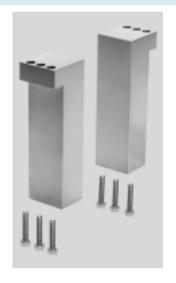
Ordering data		
	Part No.	Туре
\bigcirc	2342434	HGPLE-14-30-3,1-DC-VCSC-G96
	2342435	HGPLE-14-60-3,1-DC-VCSC-G96
	555563	HGPLE-25-40-2,8-DC-VCSC-G85
	2342436	HGPLE-25-80-2,8-DC-VCSC-G85

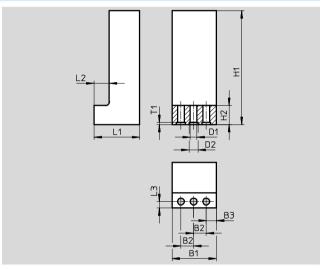
Accessories

Gripper jaw blank BUB-HGPL

(2 included in delivery)

Materials: Wrought aluminium alloy Free of copper and PTFE RoHS-compliant





Dimensions and ordering data									
For size	B1	B2	В3	D1	D2	H1	H2		
				Ø	Ø				
	+0.1	+0.02		+0.1	H8	+0.1			
14	25	8	4	3.2	5	80	11		
25	35	10	8	5.3	7	120	15		

For size	L1	L2	L3	T1	Weight per	Part No.	Туре
					blank		
	+0.1	+0.1	+0.1	+0.1	[g]		
14	20.5	8	3.3	1.3	75	537316	BUB-HGPL-14
25	36	12	5	1.6	295	537317	BUB-HGPL-25

Ordering data -	Centring sleeve		
	For size	Part No. Type	PU ¹⁾
For the gripper j	aws	Technical data →	Internet: zbh
	14	189652 ZBH-5	10
	25	186717 ZBH-7	
For the gripper		Technical data →	Internet: zbh
<u></u>	14, 25	150927 ZBH-9	10

¹⁾ Packaging unit

- New Size 14/25-80

Parallel grippers HGPLE, sturdy with long stroke, electric

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Accessories

Adapter kit

Materials:

DHAA, HAPG Wrought aluminium alloy

Free of copper and PTFE RoHS-compliant



The kit includes the individual mounting interface as well as the necessary mounting material.

Permissible drive/gripper com Combination	Drive	Drive Gripper			Adapter	kit		
	Size	Size	Mounting option		CRC ¹⁾	Part No.	Туре	
OGSL/HGPLE	DGSL	HGPLE			DHAA			
	16 عي	14				2519367	DHAA-G-G6-16-B17-14	
	20, 25	14			2	2515219	DHAA-G-G6-20-B17-14	
	25	25				539274	DHAA-G-G6-25-B17-25	
SLT/HGPLE	SLT	HGPLE			DHAA	ΠΗΔΔ		
JEI/IIUI LL	16	14		_	2.00	2531838	DHAA-G-G3-16-B17-14	
	20	14	-	_		2516304	DHAA-G-G3-20-B17-14	
	25	14	_	_	_ 2	2516252	DHAA-G-G3-25-B17-14	
	25	25	_	_		8033603	DHAA-G-G3-25-B17-25	
MP/HGPLE	НМР	HGPLE			DHAA/H	APG		
HMP/HGPLE	HMP 20, 25	HGPLE 25	-	•	DHAA/H.	APG 539887	HAPG-92	
			-	•			HAPG-92	
	20, 25	25	-	•	2		HAPG-92	
	20, 25 DRQD	25 HGPLE			2 DHAA	539887		
	20, 25 DRQD 16, 20	HGPLE		•	2	2534351	DHAA-G-Q5-16-B17-14	
	DRQD 16, 20 25, 32	HGPLE 14 25		-	DHAA 2	539887		
	DRQD 16, 20 25, 32 DRQD-E422	HGPLE 14 25 HGPL		•	2 DHAA	2534351 537311	DHAA-G-Q5-16-B17-14 HAPG-SD2-29	
	DRQD 16, 20 25, 32 DRQD-E422 16, 20	HGPLE 14 25 HGPL 14		•	DHAA 2	2534351 537311 2512383	DHAA-G-Q5-16-B17-14 HAPG-SD2-29 DHAA-G-Q5-16-B17-14-E	
	DRQD 16, 20 25, 32 DRQD-E422	HGPLE 14 25 HGPL		•	DHAA 2 DHAA	2534351 537311	DHAA-G-Q5-16-B17-14 HAPG-SD2-29	
DRQD/HGPLE	DRQD 16, 20 25, 32 DRQD-E422 16, 20 25, 32	HGPLE 14 25 HGPL 14 25 25		•	2 DHAA 2 DHAA 2	2534351 537311 2512383	DHAA-G-Q5-16-B17-14 HAPG-SD2-29 DHAA-G-Q5-16-B17-14-E	
DRQD/HGPLE	DRQD 16, 20 25, 32 DRQD-E422 16, 20 25, 32 DRRD	HGPLE 14 25 HGPL 14 25 HGPL 14 15		•	DHAA 2 DHAA	2534351 537311 2512383 544645	DHAA-G-Q5-16-B17-14 HAPG-SD2-29 DHAA-G-Q5-16-B17-14-E HAPG-SD2-46	
IRQD/HGPLE	DRQD 16, 20 25, 32 DRQD-E422 16, 20 25, 32 DRRD 16	HGPLE 14 25 HGPL 14 25 HGPL 14 14 15 16 17 18 18 18 18 18 18 18 18 18 18 18 18 18		•	2 DHAA 2 DHAA 2	2534351 537311 2512383 544645	DHAA-G-Q5-16-B17-14 HAPG-SD2-29 DHAA-G-Q5-16-B17-14-E HAPG-SD2-46 DHAA-G-Q11-16-B17-14	
IRQD/HGPLE	DRQD 16, 20 25, 32 DRQD-E422 16, 20 25, 32 DRRD 16 20	HGPLE 14 25 HGPL 14 25 HGPL 14 14 14		•	2 DHAA 2 DHAA 2	2534351 537311 2512383 544645 8034057 8034058	DHAA-G-Q5-16-B17-14 HAPG-SD2-29 DHAA-G-Q5-16-B17-14-E HAPG-SD2-46 DHAA-G-Q11-16-B17-14 DHAA-G-Q11-20-B17-14	
DRQD/HGPLE	DRQD 16, 20 25, 32 DRQD-E422 16, 20 25, 32 DRRD 16 20 25	HGPLE 14 25 HGPL 14 25 HGPL 14 14 14 14		•	2 DHAA 2 DHAA 2	2534351 537311 2512383 544645 8034057 8034058 3122168	DHAA-G-Q5-16-B17-14 HAPG-SD2-29 DHAA-G-Q5-16-B17-14-E HAPG-SD2-46 DHAA-G-Q11-16-B17-14 DHAA-G-Q11-20-B17-14 DHAA-G-Q11-25-B17-14	
DRQD/HGPLE	DRQD 16, 20 25, 32 DRQD-E422 16, 20 25, 32 DRRD 16 20 25 25 25	HGPLE 14 25 HGPL 14 25 HGPL 14 14 25			DHAA DHAA DHAA DHAA	2534351 537311 2512383 544645 8034057 8034058 3122168 8033607	DHAA-G-Q5-16-B17-14 HAPG-SD2-29 DHAA-G-Q5-16-B17-14-E HAPG-SD2-46 DHAA-G-Q11-16-B17-14 DHAA-G-Q11-20-B17-14 DHAA-G-Q11-25-B17-14 DHAA-G-Q11-25-B17-25	
HMP/HGPLE DRQD/HGPLE DRRD/HGPLE	DRQD 16, 20 25, 32 DRQD-E422 16, 20 25, 32 DRRD 16 20 25	HGPLE 14 25 HGPL 14 25 HGPL 14 14 14 14		•	DHAA DHAA DHAA DHAA	2534351 537311 2512383 544645 8034057 8034058 3122168	DHAA-G-Q5-16-B17-14 HAPG-SD2-29 DHAA-G-Q5-16-B17-14-E HAPG-SD2-46 DHAA-G-Q11-16-B17-14 DHAA-G-Q11-20-B17-14 DHAA-G-Q11-25-B17-14	

¹⁾ Corrosion resistance class CRC 2 to Festo standard FN 940070

Moderate corrosion stress. Indoor applications in which condensation may occur. External visible parts with primarily decorative requirements for the surface and which are in direct contact with the ambient atmosphere typical for industrial applications.

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Accessories

Adapter kit Material:

DHAA, HAPG Wrought aluminium alloy
Free of copper and PTFE

RoHS-compliant



The kit includes the individual mounting interface as well as the necessary mounting material.

Permissible drive/gripper com	Download CAD data → www.festo.com						
Combination	Drive	Gripper			Adapter	kit	
	Size	Size	Mounting option		CRC ¹⁾	Part No.	Туре
				A			
EGSL/HGPLE	EGSL	HGPLE			DHAA		
	45, 55	14			2	2519367	DHAA-G-G6-16-B17-14
	75	14	•			2515219	DHAA-G-G6-20-B17-14
ERMB/HGPLE	ERMB	HGPLE			HAPG		
	25, 32	25	•	•	2	537311	HAPG-SD2-29
EHMB/HGPLE	EHMB	HGPLE			HAPG		
	20	25		•	2	537311	HAPG-SD2-29

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